

## Matrix Calculus:

Given the following set of two equations in two unknowns:

$$\begin{cases} a_{11}x_1 + a_{12}x_2 = b_1 \\ a_{21}x_1 + a_{22}x_2 = b_2 \end{cases} \quad (1)$$

We wish to solve for  $x_1$  and  $x_2$ .

$$\Rightarrow \begin{array}{r} a_{22}a_{11}x_1 + a_{22}a_{12}x_2 = a_{22}b_1 \\ a_{12}a_{21}x_1 + a_{12}a_{22}x_2 = a_{12}b_2 \end{array} \left| \begin{array}{l} + \\ - \end{array} \right.$$

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$$(a_{11}a_{22} - a_{12}a_{21})x_1 = a_{22}b_1 - a_{12}b_2$$

$$\Rightarrow x_1 = \frac{a_{22}b_1 - a_{12}b_2}{a_{11}a_{22} - a_{12}a_{21}}$$

$$\Rightarrow \begin{array}{r} a_{21}a_{11}x_1 + a_{21}a_{12}x_2 = a_{21}b_1 \\ a_{11}a_{21}x_1 + a_{11}a_{22}x_2 = a_{11}b_2 \end{array} \left| \begin{array}{l} - \\ + \end{array} \right.$$

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$$(a_{11}a_{22} - a_{12}a_{21})x_2 = a_{11}b_2 - a_{21}b_1$$

$$\Rightarrow x_2 = \frac{a_{11}b_2 - a_{21}b_1}{a_{11}a_{22} - a_{12}a_{21}}$$

$$\Rightarrow \left\{ \begin{array}{l} x_1 = \frac{a_{22}}{a_{11}a_{22} - a_{12}a_{21}} \cdot b_1 + \frac{-a_{12}}{a_{11}a_{22} - a_{12}a_{21}} \cdot b_2 \\ x_2 = \frac{-a_{21}}{a_{11}a_{22} - a_{12}a_{21}} \cdot b_1 + \frac{a_{11}}{a_{11}a_{22} - a_{12}a_{21}} \cdot b_2 \end{array} \right. \quad (2)$$

Let us introduce a shorthand notation for the original problem (1):

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

or:

$$\underline{A} \cdot \underline{x} = \underline{b}$$

where:  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \in \mathbb{R}^{2 \times 2}$

is a square matrix of dimension  $2 \times 2$ ,

and:

$$\underline{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}; \quad \underline{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}; \quad \underline{x}, \underline{b} \in \mathbb{R}^2$$

are column vectors of length 2. The rules of product  $A \cdot \underline{x}$  are implicitly defined by the meaning of this notation as a shorthand for problem (1).

The solution (2) has the same structure as (1), thus, we can write:

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} \frac{a_{22}}{a_{11}a_{22} - a_{12}a_{21}} & \frac{-a_{12}}{a_{11}a_{22} - a_{12}a_{21}} \\ \frac{-a_{21}}{a_{11}a_{22} - a_{12}a_{21}} & \frac{a_{11}}{a_{11}a_{22} - a_{12}a_{21}} \end{bmatrix} \cdot \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

or:

$$\underline{x} = A^{-1} \cdot \underline{b}$$

where:

$$A^{-1} = \begin{bmatrix} \frac{a_{22}}{a_{11}a_{22} - a_{12}a_{21}} & \frac{-a_{12}}{a_{11}a_{22} - a_{12}a_{21}} \\ \frac{-a_{21}}{a_{11}a_{22} - a_{12}a_{21}} & \frac{a_{11}}{a_{11}a_{22} - a_{12}a_{21}} \end{bmatrix}$$

is the inverse of matrix  $A$ .

We notice that the four denominators are identical.

We can pull them out, and write:

$$A^{-1} = \frac{\begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix}}{a_{11}a_{22} - a_{12}a_{21}} = \frac{A^+}{|A|}$$

where:  $A^+ = \begin{bmatrix} a_{22} & -a_{12} \\ -a_{21} & a_{11} \end{bmatrix} \in \mathbb{R}^{2 \times 2}$

is the adjugate of matrix  $A$ ,

and  $|A| = a_{11}a_{22} - a_{12}a_{21} \in \mathbb{R}^1$  is the determinant of matrix  $A$ .

We now can compute solutions of 3 equations in 3 unknowns in the same manner, but I shall not do so. Instead, I shall give you the general solution in the matrix/vector shorthand notation.

Let  $A \in \mathbb{R}^{n \times n}$  be a square matrix of dimensions  $n \times n$ .

Let  $a_{ij}$  denote the element of  $A$  that is located at the intersection of the  $i^{\text{th}}$  row with the  $j^{\text{th}}$  column.

Let  $\{a_{ij}\}$  be the set of all elements  $a_{ij}$ , i.e.

$$A = \{a_{ij}\}$$

Let  $A_{ij}$  be a matrix of dimensions  $(n-1) \times (n-1)$  that has the same elements as  $A$ , except that the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column have been removed, e.g.

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\Rightarrow A_{23} = \begin{bmatrix} a_{11} & a_{12} \\ a_{31} & a_{32} \end{bmatrix}$$

Using these definitions, we can compute the determinant of an  $n \times n$  matrix  $A$  as the weighted sum of  $n$  subdeterminants of dimensions  $(n-1) \times (n-1)$ .

$$\begin{aligned} |A| &= \sum_{i=1}^n (-1)^{i+k} \cdot a_{ik} \cdot |A_{ik}| \\ &= \sum_{j=1}^n (-1)^{k+j} \cdot a_{kj} \cdot |A_{kj}| \end{aligned}$$

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where  $k$  can be any number between  $1..n$ . It is useful to pick  $k$  such that there are as many  $\emptyset$ 's in the row or column that is used as the common index, e.g.

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & \emptyset & 5 \\ 6 & \emptyset & 7 \end{bmatrix}$$

We choose  $k=2$  together with the first of the two formulae, thus:

$$|A| = -2 \cdot \begin{vmatrix} 4 & 5 \\ 6 & 7 \end{vmatrix} + \emptyset \cdot \begin{vmatrix} 1 & 3 \\ 6 & 7 \end{vmatrix}$$

$$- \emptyset \cdot \begin{vmatrix} 1 & 3 \\ 4 & 5 \end{vmatrix}$$

$$= -2 \cdot (4 \cdot 7 - 5 \cdot 6) = -2 \cdot (-2) = \underline{\underline{4}}$$

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$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & \emptyset & \emptyset \end{bmatrix}$$

We choose  $k=3$  together with the second of the two formulae, thus:

$$\begin{aligned} |A| &= 7 \cdot \begin{vmatrix} 2 & 3 \\ 5 & 6 \end{vmatrix} - \emptyset \cdot \begin{vmatrix} 1 & 3 \\ 4 & 6 \end{vmatrix} + \emptyset \cdot \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} \\ &= 7 \cdot \begin{vmatrix} 2 & 3 \\ 5 & 6 \end{vmatrix} = 7 \cdot (2 \cdot 6 - 3 \cdot 5) \\ &= 7 \cdot (-3) = \underline{\underline{-21}} \end{aligned}$$

Using these same definitions, we can compute the elements of the adjugate matrix as follows:

$$A^T = \{ (-1)^{i+j} \cdot |A_{ji}| \}$$

i.e., each element of  $A^T$  needs one subdeterminant. Since  $A^T$  contains  $n^2$  elements, the complete  $A^T$  requires  $n^2$  subdeterminants to be computed. Notice the reversal of the indices!

Example:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

$$\Rightarrow A^+ = \begin{bmatrix} \begin{vmatrix} 5 & 6 \\ 8 & 9 \end{vmatrix} & -\begin{vmatrix} 2 & 3 \\ 8 & 9 \end{vmatrix} & \begin{vmatrix} 2 & 3 \\ 5 & 6 \end{vmatrix} \\ -\begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix} & \begin{vmatrix} 1 & 3 \\ 7 & 9 \end{vmatrix} & -\begin{vmatrix} 1 & 2 \\ 4 & 6 \end{vmatrix} \\ \begin{vmatrix} 4 & 5 \\ 7 & 8 \end{vmatrix} & -\begin{vmatrix} 1 & 2 \\ 7 & 8 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} \end{bmatrix}$$

$$\Rightarrow A^+ = \begin{bmatrix} -3 & 6 & -3 \\ 6 & -12 & 6 \\ -3 & 6 & -3 \end{bmatrix}$$

Any square matrix  $A$  has an adjugate matrix  $A^+ = \text{adj}(A)$  and a determinant  $|A| = \det(A)$ . Such a matrix also has an inverse  $A^{-1} = \text{inv}(A)$  that can be computed as:

$$A^{-1} = \frac{A^+}{|A|}$$

ex:

$$\text{inv}(A) = \frac{\text{adj}(A)}{\det(A)}$$

except in the case where  $|A| = \emptyset$ . In such a case, the matrix  $A$  is called Singular.

Example:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

$$|A| = 1 \cdot \begin{vmatrix} 5 & 6 \\ 8 & 9 \end{vmatrix} - 2 \cdot \begin{vmatrix} 4 & 6 \\ 7 & 9 \end{vmatrix} + 3 \cdot \begin{vmatrix} 4 & 5 \\ 7 & 8 \end{vmatrix}$$

$$= 1 \cdot (-3) - 2 \cdot (-6) + 3 \cdot (-3)$$

$$= -3 + 12 - 9 = \emptyset$$

$\Rightarrow$   $A$  is singular. It does not possess an inverse.

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Linear systems with singular matrices usually don't have a solution:

$$A = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$$

$$\Rightarrow |A| = 4 - 4 = 0$$

Let us look at the problem:

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$$

$$\Rightarrow \begin{cases} x_1 + 2x_2 = 3 \\ 2x_1 + 4x_2 = 5 \end{cases}$$

Multiply the 1<sup>st</sup> equation with 2:

$$2x_1 + 4x_2 = 6$$

is in contradiction with the second equation.

If a linear system with a singular matrix does have a solution, the solution is not completely determined.

Let us look at the problem:

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$

$$\Rightarrow \begin{cases} x_1 + 2x_2 = 3 \\ 2x_1 + 4x_2 = 6 \end{cases}$$

The second equation is redundant.  
Any solution with:

$$x_1 = 3 - 2x_2$$

is a good solution, e.g.

$$x_1 = x_2 = 1$$

or:  $x_1 = -1$  ;  $x_2 = 2$

etc.